

IG Valley, Madurai Main Road, Manikandam, Tiruchirappalli - 620012

NAAC DOCUMENTS

QUALITY INDICATOR FRAME WORK

CRITERION – 1

CURRICULAR ASPECTS

SUBMITTED BY

IQAC INTERNAL QUALITY ASSURANCE CELL INDRA GANESAN COLLEGE OF ENGINEERING







Criteria 1

Curricular Aspects

100

- **1.1 Curricular Planning and Implementation (20)**
- 1.1.1 The Institution ensures effective curriculum planning and delivery through a well-planned and documented process including Academic calendar and conduct of continuous internal Assessment

Table of Content

S. No	Description
1.	Preface of the Course File
2.	Review of Course File
3.	Faculty Time Table
4.	Course Plan
5.	Course Committee Meeting
6.	Content Beyond Syllabus
7.	Rubrics Base Evaluation
8.	Academic Audit Form
9.	Student Feed Back on Faculty
10.	Internal Assessment Schedule
11.	Question Paper
12.	Answer Key
13.	Sample Answer Sheet
14.	Co Based Mark Entry
15.	Root Cause Analysis
16.	Retest Question Paper
17.	Retest Sample Answer Sheet
18.	Retest Co Based Mark Entry

INDRA GANESAN COLLEGE OF ENGINEERING

IG Valley, Manikandam, Tiruchirappalli, Tamil Nadu – 620 012, India (Approved by AICTE, New Delhi, Affiliated to Anna University, Chennai-25)

DEPARTMENT OF MECHANICAL ENGINEERING

PREFACE OF THE COURSE FILE

: 2017-2021
: 2021-2022 / EVEN
: MECHANICAL ENGINEERING
: 4 th Year / 8 th Semester
: ME8094 : Computer Integrated Manufacturing Systems
: Mr.R. Ramesh Babu, AP/Mechanical

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INDRA GANESAN COLLEGE OF ENGINEERING

IG Valley, Manikandam, Tiruchirappalli, Tamil Nadu – 620 012, India (Approved by AICTE, New Delhi, Affiliated to Anna University, Chennai-25)

DEPARTMENT OF MECHANICAL ENGINEERING

Proof of Conduct of Content Beyond Syllabus(CBS)

Name of the Faculty : Mr.R.Ramesh Babu Course Code & Name: ME8094 Computer Integrated Manufacturing Systems

Degree & Program: B.E., /Mechanical Semester: VIII Academic

Semester: VIII Academic Year: 2021 -2022 /EVEN

TOPIC: SIX INDUSTRIAL ROBOTICS TRENDS

INTRODUCTION:

Robotics are becoming more important and manufacturers are recognizing their growing role in many different industries and applications. Six industry trends are highlighted.

Industrial robotics insights

- Robotics are being used more often in industrial manufacturing facilities due to a rising labor and skills gap and strong industry demand.
- Trends in the industrial robotics market include increased digitalization and automation and an emphasis on making robots easier to use.
- Sustainability is a growing trend throughout manufacturing and industrial robots are no exception.

1. Labor and demographics

Scott Marsic, group product manager – robotics, at Epson America Inc. said labor shortages are "far and away, the number one trend" driving industrial automation adoption.

"The United States' manufacturing sector is doing great work, but there are more jobs than there are people to fill them and that presents a problem."Labor issues are global, said Kary Zate, senior director, marketing communications at Locus Robotics. "You've got labor shortages, an aging population in the warehouse, and a younger generation that's not really interested in working in warehouse environments, because, frankly, it's hard work that requires people to walk 10 to 15 miles a day in a cart-based environment. It's very taxing."With finding and retaining talent a major challenge for industry, a growing number of companies are turning to industrial automation to fill labor gaps, improve productivity, and stay competitive in a challenging macroeconomic landscape, Zate said.

2. Digitalization drives

The pandemic accelerated both automation adoption and the digital transformation across the industrial sector, said Lian Jye Su, research director at market analyst firm ABI Research.

"This trend includes remote monitoring software and software that enables or otherwise facilitates the adoption of industrial automation," said Su. "There is no faster way to automate, especially when deploying a mix of robot brands, than to use these types of software. The traditional approach – hiring engineers to commission a robotic solution—can take weeks and months and that means a missed opportunity for a lot of these manufacturers."Explore any industry tradeshow and you will find a wide range of digitalization tools from AI and augmented reality to digital twins geared towards manufacturing applications. Marsic said.

"It's an exciting time in robotics and digitalization and these technologies are helping to attract new folks to robotics programming roles. For a programmer, the opportunity to work with AI and augmented reality and have their code deployed on industrial robots is pretty cool."

3. Cobot and mobile robot use increasing

Collaborative robots remain the fastest growing segment of the industrial robotics sector, Su said. "There's been a lot of positive feedback in recent years about how cobots are easy to deploy and, over time, cobots have found their niche in the industrial robotics sector and it has proven to be one that can complement both human labor and traditional industrial robots. I don't think that growth is slowing down any time soon."According to ABI Research, the cobot market had a global valuation of \$475 million in 2020, expanded to \$600 million in 2021 and is expected to reach \$8 billion by 2030, at a projected CAGR of 32.5%. At the same time, mobile robots are also seeing rapid surge in popularity, Su said. "Just ten years ago, mobile robots were a luxury, now they are found in almost every industry segment and location from deep sea oil rigs to manufacturing and warehouse facilities."Global robotics Venture Capital (VC) investment reached US\$5.7 billion in 2021, at 38% year-on-year growth, with autonomous mobile robots attracting huge interest, according to ABI Research.

4. Reshoring initiatives

Labor costs overseas are rising quickly, while at the same time, the cost of automation is dropping significantly. These are just two of the factors that are helping to drive reshoring initiatives across the United States and other leading economies, Masic said."Today, there are several additional issues to contend with from intellectual property and tariffs to geopolitics, and supply chain challenges. Companies need to bring back manufacturing quickly and the best way to do that, especially in the middle of a labor crisis, is with automation."And by shortening supply lines, reshoring can also reduce emissions and generate environmental benefits that help to make manufacturing more sustainable.

5. Robots are becoming more usable

The increasing usability of industrial robot systems makes it easier than ever for companies of all sizes and technical skill levels to deploy automation."The drive for simplicity is a really important trend," Masic said. "People want to get their automation up and running quickly. This requires an easy-to-use operating system and extensive customer support throughout the entire process. The need for simplicity is being driven by new customers and new users coming into the automation space. We saw this trend before the pandemic, but since 2020 it has really blown up."The rising popularity of the robotics-as-a-service model has made automation adoption easier and less capital intensive, giving operators the ability to seamlessly scale to meet changing volumes and seasonal spikes in just minutes vs. the typical time frames that can take weeks or months, Zate said.

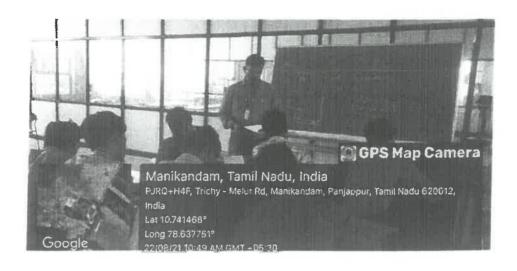
6. Increased focus on sustainability

There is growing concern around sustainability and climate issues among robot manufacturers and their customers, Masic said. "Sustainability and environmental responsibility are long-time core values of the Epson organization. For example, by moving away from ground-based sources of materials as much as possible and by exploring the whole lifecycle of our products to discover which parts can be reused."From the outset, Locus Robotics developed its business model based on sustainability principles, including widespread refurbishment of parts, Zate said.

Website Referencce:

https://www.sciencedirect.com/science/article/abs/pii/S0736584599000368

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Signature of the Raculty in-charge

HoD Mechanical

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Indra Ganesan

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SI No	Conte nts	Course Code	Course Name	Year/S mester	- I I	. 7	P	Credits	Contact Periods	Total
			I YEAR MECHANICA	L	_	-	_			
1	ă	GE8152	Engineering Graphics	I/II	2	0	4	4	5	90
3	THEOR Y	BE8252	Basic Civil and Mechanical Engineering	Ι/Π	3	0	0	4	3	45
4	F	PH8251	Materials Science	I/II	3	0	0	3	3	45
1	LAB	GE8261	Engineering Practices Laboratory	1/11	0	0	4	2	4	60
			II YEAR MECHANICA	L	_	-	-			
1	T	MA8452	Statistics and Numerical Methods	II/IV	4	0	0	4	4	60
2	~ [ME8492	Kinematics of Machinery	II/IV	3	0	0	3	3	45
3	THEORY	ME8451	Manufacturing Technology - II		3	0	0	3	3	45
4	ME8491		Engineering Metalluray	II/IV	3	0	0	3	3	45
5	F [CE8395	Strength of Materials for Mechanical Engineering	I/IV	3	0	0	3	0	45
6	Γ	ME8493	Thermal Engineering- I	II/IV	3	0	0	3	3	45
1		ME8462	Manufacturing Technology Laboratory ~ II		0	0	4	2	4	60
2	LAB	CE8381	Strength of Materials and Fluid Mechanics and Machinery La		0	0	4	2	4	60
3	- 1	HS8461	Advanced Reading and Writing		0	0	2	1	2	30
			III YEAR MECHANICAL		10	V	4	*	her .	
1	T	ME8651	Design of Transmission Systems		3	Ð	0	3	3	45
2	- 1	ME8691	Computer Aided Design and Manufacturing	III/VI	3	0	0	3	3	45
3	T	ME8693	Heat and Mass Transfer		3	2	0	4	5	75
4	8 h	ME8692	Finite Element Analysis		3	0	0	3	3	45
5	F []	ME8694	Hydraulics and Pneumatics		3	0	0	3	3	45
6	1	ME8091	Automobile Engineering (Professional Elective - I)		3	0	0	3	3	45
1	1	ME8681	CAD / CAM Laboratory	III/VI	0	0	4	2	4	60
2	I AB	ME8682	Design and Fabrication Project	III / VI	0	0	4	2	4	60
3		HS8581	Professional Communication	III/VI	0	0	2	1	2	30
			IV YEAR MECHANICAL	A34 / 7 A	0	0	4	1	4	30
1	N N	1G8591	Principles of Management	IV / VIII	3	0	0.	3	3	45
2	THEORY	E8693	Production planning and Control (Professional Elective- IV)	IV / VIII	3	0	0	3	3	45
	m N	1E8811	Project Work	IV / VIII	0	0	20	10	20	300

S.No	Year	No. of Theory Subject	No. of Laboratory	
1	I	4	1	
2	п	5	2	-
3	Ш	6	2	
4	IV	2	1	
TOT	AL	16	6	

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_			epartment of Mechanical Engineering				
			load Allocation - Even Semester 2021-20	22			
S.NO.	Staff Name	Course	Course Name	Semester	Credits	Lecture / week	Tota
		ME8094	Computer Integrated Manufacturing Systems	VIII	3	4	
	i tron h Taka	ME8691	Computer Aided Design and Manufacturing	VI	3	4	
1	Mr.R.Ramesh Babu HOD/Mech	ME8491	Engineering Metallurgy	IV	3	4	36
		ME8682	Design and Fabrication Project	VI	2	4	
	(3+2)	ME8811	Project Work	VIII	10	20	
		ME8451	Manufacturing Technology – Il	IV	3	4	
	Dr. V.Vaithiyanathan AP/Mech	ME8651	Design of Transmission Systems	VI	3	4	16
3	AF/meun	PH8251	Materials Science	II	3	4	20
	(3+1)	ME8681	CAD / CAM Laboratory	VI	2	4	
		ME8693	Heat and Mass Transfer	VI	4	5	
	Mr.T.David Ubahara	ME8492	Kinematics of Machinery	ſV	3	4	17
4	Samy AP/Mech (3+1)	CE8395	Strength of Materials	ſV	3	4	
		CE8381	Strength of Materials and Fluid Mechanics and Machinery Lab	IV	2	4	
		ME8493	Thermal Engineering- I	IV	3	4	
	Mr.G. Deepan Kumar AP/Mech	ME8694	Hydraulics and Pneumatics	٧ĩ	3	4	16
5	ne j mour	ME8091	Automobile Engineering	vī	3	4	
	(3+1)	ME8462	Manufacturing Technology Laboratory - II	IV	2	4	
		GE8152	Engineering Graphics (A Section)	1	4	6	
	Mr.M	BE8252	Basic Civil and Mechanical Engineering	Ш	4	5	18
6	Kamalakannan/Mech (3+1)	IE8693	Production Planning and Control	VIII	3	4	
		GE8261	Engineering Practices Laboratory ('B' Sections)	n	2	4	-100+100
		ME8692	Finite Element Analysis	VI	3	4	
	S.Rahul Bharath MG8591 Principles of	Principles of Management	vm	3	4	18	
7	AP/Mech (3+1)	GE8152	Engineering Graphics (A Section)	I	4	б	~ ~
	f.e. , wh	GE8261	Engineering Practices Laboratory ('A' Sections)	D	2	4	

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ME8094 COMPUTER INTEGRATED MANUFACTURING SYSTEMS L T P C

OBJECTIVE:

To understand the application of computers in various aspects of Manufacturing viz., Design, Proper planning, Manufacturing cost, Layout & Material Handling system.

UNIT I INTRODUCTION

Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control- Introduction to CAD/CAM – Concurrent Engineering-CIM concepts – Computerised elements of CIM system – Types of production - Manufacturing models and Metrics – Mathematical models of Production Performance – Simple problems – Manufacturing Control – Simple Problems – Basic Elements of an Automated system – Levels of Automation – Lean Production and Just-In-Time Production.

UNIT II PRODUCTION PLANNING AND CONTROL AND COMPUTERISED PROCESS PLANNING

Process planning – Computer Aided Process Planning (CAPP) – Logical steps in Computer Aided Process Planning – Aggregate Production Planning and the Master Production Schedule – Material Requirement planning – Capacity Planning- Control Systems-Shop Floor Control-Inventory Control – Brief on Manufacturing Resource Planning-II (MRP-II) & Enterprise Resource Planning (ERP) - Simple Problems.

UNIT III CELLULAR MANUFACTURING

Group Technology(GT), Part Families – Parts Classification and coding – Simple Problems in Opitz Part Coding system – Production flow Analysis – Cellular Manufacturing – Composite part concept – Machine cell design and layout – Quantitative analysis in Cellular Manufacturing – Rank Order Clustering Method - Arranging Machines in a GT cell – Hollier Method – Simple Problems,

UNIT IV FLEXIBLE MANUFACTURING SYSTEM (FMS) AND AUTOMATED GUIDED VEHICLE SYSTEM (AGVS)

Types of Flexibility - FMS – FMS Components – FMS Application & Benefits – FMS Planning and Control – Quantitative analysis in FMS – Simple Problems. Automated Guided Vehicle System (AGVS) – AGVS Application – Vehicle Guidance technology – Vehicle Management & Safety.

UNIT V INDUSTRIAL ROBOTICS

Robot Anatomy and Related Attributes – Classification of Robots- Robot Control systems – End Effectors – Sensors in Robotics – Robot Accuracy and Repeatability - Industrial Robot Applications – Robot Part Programming – Robot Accuracy and Repeatability – Simple Problems.

TOTAL: 45 PERIODS

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OUTCOMES:

- CO1 Explain the basic concepts of CAD, CAM and computer integrated manufacturing systems
- CO2 Summarize the production planning and control and computerized process planning
- CO3 Differentiate the different coding systems used in group technology
- CO4 Explain the concepts of flexible manufacturing system (FMS) and automated guided vehicle (AGV) system
- CO5 Classification of robots used in industrial applications
- CO6 Explain the Robot control systems and part programming.

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DEPARTMENT OF MECHANICAL ENGINEERING

Identification of Curricular Gap & Content Beyond Syllabus(CBS)

Name of the Faculty :: Mr.R.Ramesh Babu Course Code & Name: ME8094-Computer Integrated Manufacturing Systems

Degree & Program; B.E. /Mechanical Semester: VIII Academic Year: 2021 -2022 /EVEN

I.Mapping of Course Outcomes with POs & PSOs.(before CBS)

Course	PO1	PO2	PO3									PO12	PSO1	PSO2	PSO3
CO411.1	3	3		-	2	-	1	-	1			286	3	3	2
CO411.2	3	3	-	-	2	-	1	-	1		-	-	3	2	2
CO411.3	3	3		-	2	-	1	-	1	-	-		3	2	2
CO411.4	3	3		-	2	- 2013/24	1	-	1	-	-		3	2	2
CO411.5	3	3	-		-		1	-	1	-	-	-	3	2	2
CO411.6	3	3	- 100		2	-	1	-	1	-	-	- 1	3	2	2
CO411	3	3		-	2	-	1	-	1	-	-	-]	3	2	3

Table.1 Mapping of COs, C, PSOs with POs - before CBS.

II. Identification of content beyond syllabus.

Table.2 Identification of content beyond syllabus

Details of Content Beyond Syllabus(CBS) added	POs strengthened/ vacant filled	CO/Unit
Six Industrial Robotics Trends	PO4 & PO5 (1) Vacant filled	CO411.5 V

III. Mapping of Course Outcomes with POs & PSOs. (After CBS)

Table.3 Mapping of COs, C, PSOs with POs- after CBS.

										TTAGEL A S			4 44 447		
Course	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO411.1	3	3	-	-	2	-	1	-	1	-	-	-	3	2	2
CO411.2	3	3	-	-	2	-	1	-	1	-	-44	-	2	2	2
CO411.3	3	3	-	-	2	-	1	-	1	-	-	-	2	2	2
CO411.4	3	3	**	-	2	~	1	-	1		-	-	2	2	2
CO411.5	3	3	-	*2	*2	- 1	1	-	1	-		-	2	2	2
CO411.6	3	3		-	2		I		I	a la fair a sta a constant a fair	-	-	2	2	2
CO411	3	3	-	-	2	-	1	H	1	-	•	-	2	2	2

Signature of the Faculty

10		2	Levels of Automation	TI
11		5	Lean Production and Just-In-Time Production	T1
12		6	Simple problems	T1
UNI	TII -PROL	UCTI	ON PLANNING AND CONTROL AND COMPUTERISED PROCES	SS
	NNING		Target	eriods :0
13	28.03.22	2	Process planning	T1
14	29.03.22	2	Computer Aided Process Planning (CAPP)	T1
15	30.03.22	5	Logical steps in Computer Aided Process Planning	T2
16	04.04.22	2	Aggregate Production Planning and the Master Production Schedule	T2
17	05.04.22	2	Aggregate Production Planning and the Master Production Schedule	R1
18	06.04.22	5	Material Requirement planning	R1
19	08.04.22	6	Capacity Planning- Control Systems	R1
20	09.04.22	2	Shop Floor Control-Inventory Control	R1
21	11.04.22	2	Brief on Manufacturing Resource Planning-II (MRP-II)	T1
22	12.04.22	2	Enterprise Resource Planning (ERP)	T1
23	13.04.22	5	Simple Problems	TI
	2 · · · · · · · · · · · · · · · · · · ·	Tradaption.	And the second	eriods :0
24	15.04.22	6	Group Technology(GT)	T1
25	23.04.22	2	Part Families – Parts Classification and coding	T1
26	25.04.22	2	Simple Problems in Opitz Part Coding system	T1
27	26.04.22	2	Production flow Analysis - Cellular Manufacturing	T2
28	27.04.22	5	Composite part concept	T2
29	29.04.22	6	Machine cell design and layout	T2
30	02.05.22	2	Quantitative analysis in Cellular Manufacturing	T2
31	03.05.22	2	Rank Order Clustering Method	R2
32	04.05.22	5	Arranging Machines in a GT cell	R2
33	06.05.22	6	Simple Problems	R2
34	07.05.22	2	Hollier Method	R3
35	09.05.22	2	Simple Problems	R3
INIT	IV - FLEX	BLEI	MANUFACTURING SYSTEM (FMS) AND AUTOMATED GUIDEI)
EHI	CLE SYSTE	EM (A	GVS) Target P	
36	10.05.22	2	Types of Flexibility - FMS	T2
37	11.05.22	5	FMS Components	T2
38	13.05.22	6	FMS Application & Benefits	T2
39	16.05.22	2	FMS Planning and Control	T2
40	17.05.22	2	Quantitative analysis in FMS	T2
TU			Simple Problems	T2
41	18.05.22	5		
**************************************	18.05.22 20.05.22	5 6	Simple Problems	T2
41	the second se		Simple Problems Automated Guided Vehicle System (AGVS), AGVS Application	Antimetricity and the appleases we are
41 42	20.05.22	6		T2 R3_
41 42 43	20.05.22 23.05.22	6 2	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology	T2 R3 R3
41 42 43 44 45	20.05.2223.05.2224.05.2225.05.22	6 2 2 5	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety	T2 R3 R3 R3
41 42 43 44 45 NIT	20.05.2223.05.2224.05.2225.05.22	6 2 2 5	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety ROBOTICS Target Pe	T2 R3 R3 R3 riods:09
41 42 43 44 45 NIT 46	20.05.22 23.05.22 24.05.22 25.05.22 V – INDUS	6 2 2 5 IRIAI 6	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety ROBOTICS Target Pe Robot Anatomy and Related Attributes	T2 R3 R3 R3 riods:09 T2
41 42 43 44 45 NIT 46 47	20.05.22 23.05.22 24.05.22 25.05.22 V - INDUS 27.05.22 30.05.22	6 2 2 5 IRIAI	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety ROBOTICS Target Pe Robot Anatomy and Related Attributes Classification of Robots	T2 R3 R3 R3 riods:09 T2 T2 T2
41 42 43 44 45 NIT 46 47 48	20.05.22 23.05.22 24.05.22 25.05.22 V - INDUS' 27.05.22 30.05.22 31.05.22	6 2 5 IRIAI 6 2 2	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety ROBOTICS Target Performance Robot Anatomy and Related Attributes Classification of Robots Robot Control systems	T2 R3 R3 R3 riods:09 T2 T2 T2 T2
41 42 43 44 45 NIT 46 47 48 49	20.05.22 23.05.22 24.05.22 25.05.22 V - INDUS 27.05.22 30.05.22	6 2 2 5 IRIAI 6 2	Automated Guided Vehicle System (AGVS), AGVS Application Vehicle Guidance technology Vehicle Management & Safety ROBOTICS Target Pe Robot Anatomy and Related Attributes Classification of Robots	T2 R3 R3 R3 riods:09 T2 T2 T2

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DEPARTMENT OF MECHANICAL ENGINEERING

Lecture Schedule

Degree/Program: B.E / MECHANICAL	Course code &Name	: ME 8094-Computer Integrated
		Manufacturing System
Duration: Dec 2021 - Apr 2022	Semester: VIII	Faculty: Mr. R. Ramesh Babu

<u>AIM:</u>

To expose the students to introduction to CAD and CAM, Computer Aided Process Planning, Cellular Manufacturing, Flexible Manufacturing System, & Industrial Robot Applications.

OBJECTIVES:

To understand the application of computers in various aspects of Manufacturing viz., Design, Proper planning, Manufacturing cost, Layout & Material Handling system.

PREREOUISITES: Computer Integrated Manufacturing System

COURSE OUTCOMES:

After the course, the student should be able to:

CO	Course Outcomes	POs	PSOs
CO411.1	Explain the basic concepts of CAD, CAM and computer integrated manufacturing systems	1,2,5,7,9	1,2,3
CO411.2	Summarize the production planning and control and computerized process planning	1,2,5,7,9	1,2,3
CO411.3	Differentiate the different coding systems used in group technology	1,2,5,7,9	1,2,3
CO411.4	Explain the concepts of flexible manufacturing system (FMS) and automated guided vehicle (AGV) system	1,2,5,7,9	1,2,3
CO411.5	Classification of robots used in industrial applications	1,2,7,9	1,2,3
CO411.6	Application of robotics in vehicle management and safety.	1,2,5,7,9	1,2,3

S.No	Date	Period	Topics to be Covered	Book & Page. No.
UNIT	-I - INTE	RODUCT	TON Target p	eriods :09
1	07.03.22	2	Brief introduction to CAD and CAM	T1
2	08.03.22	2	Manufacturing Planning, Manufacturing control- Introduction to CAD/CAM	T1
3	09.03.22	5	Concurrent Engineering CIM concepts	T1
4	11.03.22	6	Computerised elements of CIM system	T1
5	14.03.22	2	Types of production	T1
6	15.03.22	2	Manufacturing models and Metrics	R2
7	16.03.22	5	Mathematical models of Production Performance - Simple problems	T1
8	18.03.22	6	Manufacturing Control - Simple Problems	T1
9	21.03.22	2	Basic Elements of an Automated system	R2

TEXT BOOKS:

- 1. Mikell.P.Groover "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2008.
- 2. Radhakrishnan P, Subramanyan S.and Raju V., "CAD/CAM/CIM", 2nd Edition, New Age International (P) Ltd, New Delhi, 2000.

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- 1. Gideon Halevi and Roland Weill, "Principles of Process Planning A Logical Approach" Chapman & Hall, London, 1995.
- Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall India.
 Rao. P, N Tewari &T.K. Kundra, "Computer Aided Manufacturing", Tata McGraw Hill Publishing Company, 2000.

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DEPARTMENT OF MECHANICAL ENGINEERING

Assignment Answer Sheet

Name of the Student : A. Shameer

AU Register Number: 811217 114 031

			Date of Issue:	10.02.2021	Marks 10
-SAGAR	Assignment	Course Title	Computer Integra	ted Manufacturing S	ystems
Course code	ME8094	Contraction in the second	a mine a b	Date of Submiss	ion: 14.02.2021
Year	IV	Semester/Section	AITNU		and the second second

	Ouestions	CO
Q.No		C411.1
1	Explain the hierarchical structure of Computerized elements of CIM	C411.1
2	Explain in detail about Kanban System and its types with example.	CHIM

Mark Allocation

Rubrics	Marks Allocated	Marks obtained
Content Quality	6	6
Presentation Quality	2	2
Timely submission	2	2
Total marks	10	10

2. DAMESH BABU

Name and Signature of the Faculty Incharge

Dr.G. Bildirithnan, M.S. Phistoph InddraGaessar Godugerof Choire. Igowilley, Madout Main Post



Mandang Trichy-520 012.

INDRA GANESAN COLLEGE OF ENGINEERING IG Valley, Manikandam, Tiruchirappalli, Tamil Nadu – 620 012, India (Approved by AICTE, New Delhi, Affiliated to Anna University, Chennai-25)

DEPARTMENT OF MECHANICAL ENGINEERING

Assignment Question Paper

	Assignment - ()1	Date of Issue:	10.02.2021	Marks	10
Course code	ME8094	Course Title	Computer Integrated Manufacturing Systems			
Year	IV	Semester/Section	VIII/A	Date of Submissi	on: 14.02.	2021

Q.No	Questions	CO
1	Explain the hierarchical structure of Computerized elements of CIM	C411.1
2	Explain in detail about Kanban system and its types with example.	C411.1

Name and Signature of the Faculty Incharge

52	07.06.22	2	Robot Part Programming	R1
53	08.06.22	5	Robot Accuracy and Repeatability	T2
54	10.06.22	6	Simple Problems	T2
			Content Beyond the Syllabus	
52	11.06.22	6	Six Industrial Robotics Trends	Material

Book Reference - Text Books

Sl.	Title of the Book	Author	Publisher	Year
1.	Automation, Production Systems and Computer Integrated Manufacturing	Mikell.P.Groover	Prentice Hall of India	2008.
2.	CAD/CAM/CIM	Radhakrishnan P, Subramanyan S.and Raju V.	2nd Edition, New Age International (P) Ltd, New Delhi	2000

Book Reference – References

SI	Title of the Book	Author	Publisher	Year
1.	Principles of Process Planning – A Logical Approach	Gideon Halevi and Roland Weill,	Chapman & Hall, London	1995.
2.	Principles of Computer Integrated Manufacturing	Kant Vajpayee S	Prentice Hall India	1995
3.	Computer Aided Manufacturing	Rao. P, N Tewari &T.K. Kundra	Tata McGraw Hill Publishing Company	2000.

Website Reference:

https://www.youtube.com/watch?v=jpP0zBFmQ9g https://onlinecourses.nptel.ac.in/noc23_me143/preview

Signature of the Faculty in-charge

HoD Mechanical

Register Number:



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	Internal Assessment E:	am – I – Key Notes	Date	M	arks 50
Course of	code ME 8094	Course Title	Computer Integ	grated Manufacturing Sy	vstems
Regulati	ion 2017	Duration	90 minutes	Academic Year	2021-22
Year	IV	Semester	VIII	Department	Mechanical Engg
COURS	E OUTCOMES				
CO1:	Explain the basic conc	epts of CAD, CAM and cor	nouter integrated manuf	facturing systems	
CO2:	Summarize the produc	tion planning and control ar	nd computerized proces	s planning	
CO3:	Differentiate the differ	ent coding systems used in	group technology	- producting	
CO4:	Explain the concepts of	f flexible manufacturing sys	stem (FMS) and automa	ited mided vehicle (AGV) system
CO5:	Classification of robot	used in industrial applicati	ons	and Porded Actions (110)	/ 5/040181
CO6:		rol systems and part progra			

Q.No.		CO	BT
	PART A		
1	(Answer all the Questions 10 x 2 = 20 Marks) State desirable features of CAD package.		
	Ans:		
	1. Managing various file manipulation in the computer		
	2. Loading computer programs into memory and controlling the execution of	CO411.1	KI
	program.		Î
	3. Create environment torun the application softwares.	a	
2	List some features of AUTO CAM system. Ans:		
	1. Geometry of the part can be drawn easily by using the available geometric		
	entities. It is also possible to modify the part as per our requirements. The	CO411.1	
	dimensions and other annotations required for drafting can also be defined.		K2
	2. Standards are available to convert the CAD database into manufacturing		
	database.		
3	List out some advantages of AUTOCAM Ans:		
	1. Creation of part program is easy.		
	2. The time required to create the part program is minimized.		
	3. The error in part program is minimized.	CO411.1	K2
	4. The part program can be easily modified.	1	
	5. The overall productivity of CAD/CAM system is increased.		
	What do you mean by wireframe modeling? Ans:		
	The word "wireframe" is related to the fact that one may imagine a wire that is	004414	
	bent to follow the object edges to generate the model. Typically, a wireframe model	CO411.1	K1
	consists entirely of points, lines, arcs and circles, conics, and curves.		
	What are the advantages of wire frame modeling	CO411.1	K1

			Regi	ster Number:		
C		RA GANESAN Valley, Manikandan proved by AICTE, New	n, Tiruchirappalli,	Tamil Nadu – 620 0	12, Indi	a
	Internal Assessm	ent Exam - I	Date	Ma	arks	50
Course c	ode ME 8094	Course Title	Computer Integ	rated Manufacturing Sy	stems	
Regulatio	on 2017	Duration	90 minutes	Academic Year	2021-2	22
Year	IV	Semester	VIII	Department	Mech	anical Engg
COURSE	OUTCOMES					
CO1:		pts of CAD, CAM and con				
CO2:	Summarize the product	tion planning and control an	id computerized proces	s planning		
CO3:	Differentiate the different	ent coding systems used in p	group technology	,		
CO4:	Explain the concepts of	flexible manufacturing sys	tem (FMS) and automa	ted guided vehicle (AGV) system	
CO5:		used in industrial application		ανικη το στο της Σαζαγουτική του που της μεγοργασια δελολές δελολές δεν το στο τέρι Ναγγαριατικό του που που π Τ		
CO6:	Explain the Robot cont	rol systems and part program	mming.		***********	

Q.No.	Question	CO	BTS
	PART A		
	(Answer all the Questions 10 x 2 = 20 Marks)		
1	State desirable features of CAD package.	CO411.1	K1
2	List some features of AUTO CAM system.	CO411.1	K2
3	List out some advantages of AUTOCAM	CO411.1	K2
4	What do you mean by wireframe modeling?	CO411.1	K1
5	What are the advantages of wire frame modeling?	CO411.1	K.1
6	What are the advantages of solid modeling?	CO411.1	KI
7	What are the drawing features of CAD package?	CO411.1	KI
8	What are the goals of automation in manufacturing industry?	CO411.1	K1
9	Give the classification of automation.	CO411.1	K1
10	What are the function of automated manufacturing system?	CO411.1	K1
	PART B		
_	(Answer all the Questions $2 \ge 10 = 20$ Marks)		
11a	Discuss about the operator input devices used in graphics work station (2012) (2013)	CO411.1	K2
	OR		
11b	Briefly describe 3D transformations for scaling, translation & rotation. (2014)	CO411.1	K2
12a	Write in detail about production performance metrics.	CO411.1	K2
	OR		
12b	Write short notes on generative NC machining based on solid modeling.	CO411.1	K2
	PART C		
	(Answer all the Questions $1 \ge 10$ Marks)		
13a	The average part produced in a certain batch manufacturing plant must be processed sequentially through six machines on average .Twenty (20) new batches of parts launched each week .Average operation time	CO411.1	K2
	=6min., average setup time =5hours, average batch size=36 parts, and average non operation time per batch=10hr/machine. There are 18 machines in the plant working in parallel. Each of the machines can be set up for any type of job processed in the plant. The plant operates an average of 70 production hour per week. Scrap rate is negligible. Determine (a) manufacturing lead time for an average part, (b)plant		
	capacity,(c)plant utilization(2016)		
01	OR	CONTRACT	17.0
136	Explain the concept of Lean manufacturing and Just in time production systems. (2016)	CO411.1	K2

Course Faculty

(Name /Sign / Date)

Dr. G. Balakrishnan, M.E., Ph.D., Principal Indra Ganesan College of Engineering IG Valley, Madurai Main Road Manikandam, Trichy-620 012.

(Name /Sign / Date)

	Description 5 marks		1
	OR	-L	
12b	Write short notes on generative NC machining based on solid modeling. Ans: Diagram – 5 marks Description – 5 marks	CO411.1	K2
	PART C	1	
	(Answer all the Questions 1 x 10 = 10 Marks)		
13a	The average part produced in a certain batch manufacturing plant must be processed sequentially through six machines on average .Twenty (20) new batches of parts launched each week .Average operation time 6min., average setup time =5hours, average batch size=36 parts, and average non operation time per batch=10hr/machine. There are 18 machines in the plant working in parallel. Each of the machines can be set up for any type of job processed in the plant. The plant operates an average of 70 production hour per week. Scrap rate is negligible. Determine (a) manufacturing lead time for an average part, (b)plant capacity,(c)plant utilization(2016) Ans: Diagram - 5 marks Description - 5 marks	CO411.1	K2
	OR		
l3b	Explain the concept of Lean manufacturing and Just -in -time production systems. (2016) Ans: Diagram - 5 marks Description - 5 marks	CO411.1	K2

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(Name /Sign / Date)

		1000	
	1. Simple to construct.		
	2. Designer needs little training.		
	3. It needs less memory space.		
	4. It takes less manipulation time.		
6	What are the advantages of solid modeling? Ans:		
	1. It is complete and unambiguous.		
	2. Suitable for automated applications like creating part program without much		
	human involvement.	CO411.1	KI
	3. Creation is fast.		
	4. It gives more information.		
_		anguya a an a di di dana an	
7	What are the drawing features of CAD package? Ans:	-	
	1. Geometry of the part can be drawn easily by using the available geometric		
	entities. It is also possible to modify the part as per our requirements. The	CO411.1	I К2
	dimensions and other annotations required for drafting can also be defined.		
	2. Standards are available to convert the CAD database into manufacturing		1
	database.		
8	What are the goals of automation in manufacturing industry? Ans:		
	Automation has the following primary goals.	1	
	i) Process Integration	00411.1	К2
	ii) Improve Productivity	CO411.1	K.2
	iii) Economize on floor space		
	v) Improve quality		
9	Give the classification of automation.		
	Ans: Automated manufacturing systems can be classified into three basic types:		
	1) Fixed automation	CO411.1	K1
	2) Programmable automation		
	3) Flexible automation		
10	What are the function of automated manufacturing system?		
	Ans:	and Malana	
	Automating manufacturing systems operate in the factory on the physical product. They	CO411.1	KI
	perform operations such as processing, assembly, inspection, or material handing, in		
	some cases accomplishing more than one of these operations in the same systems.		
	PART B (Answer all the Questions 2 x 10 = 20 Marks)		
11a	Discuss about the operator input devices used in graphics work station (2012) (2013)		
	Ans: Diagram – 5 marks	CO411.1	K 2
	Description – 5 marks		
11b	OR Briefly describe 3D transformations for scaling, translation & rotation. (2014)		
110	Ans:	CO411.1	К2
	Diagram – 5 marks Description – 5 marks	001111	
12a	Write in detail about production performance metrics.		
	Ans:	CO411.1	K2
100000	Diagram – 5 marks Dr. G. Balakrishnan, M.E., Ph.D.,		_
	Principal		
	Indra Ganesan College of Engineering		
	IG Valley, Madurai Main Road		
	Manikandam, Trichy-520 000		

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IG Valley, Manikandam, Tiruchirappalli, Tamii Nadu - 622 012, India (Approved by AICTE, New Delhi and affiliated to Anna University, Chennai)

Name	D. MADHAN			Vear/ Semester	IV/Vin
Reg No.	811217114016	Date/Session	19/4/22-FN	Department	MECHANIC
Course code	ME8094	Course Title	CIMS		
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Name and Sig	nature of the Invigi	ator with date	G. DEE	G. J. Org	14/22

Internal Assessment Test Answer Book

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		Audit - Ren	9	/		of the IQ	AC member		

Dr. G. Balakrishnan, M.E., Ph.D., Principal Indra Ganesan College of Engineering IG Valley, Madurai Main Road Manikandam, Trichy-620 012.

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INDRA GANESAN COLLEGE OF ENGINEERING IG VALLEY, MANIDANDAM, TIRUCHIRAPPALLI – 620 012 DEPARTMENT OF MECHANICAL ENGINEERING ACADEMIC YEAR 2021 – 2022 (EVEN SEMESTER) <u>STUDENTS MARK STATEMENT- CO BASED</u> INTERNAL ASSESSMENT TEST – I

SUBJECT CODE & TITLE: ME8094 & COMPUTER INTEGRATED MANUFACTURING SYSTEM

YEAR/SEM: IV/VIII

MONTH & YEAR: MAR & 2022

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1	811217114001	S.Abdul Yasin	50	-	-	-	-	-	41	-	1	-	-	-	82
2	811217114002	R.Ajithkumar	50	-	-	-	•	-	40	-	-	-		-	80
3	811217114003	S.Anandha Kumar	50		•	-	- 1	-	35	-	-	-	•	•	70
4	811217114004	M.Ananth	50	-	-	-	-	-	42	-	-	-	•	-	84
5	811217114005	R.Chellaiah	50	-	-	-	-	-	38	~	-	-		-	76
6	811217114006	C.Devarajan	50	-	-	-	-	-	34	•	-	-	-	-	68
7	811217114007	S.Dhamotharan	50	-	-	-	-	-	28	-	-	-	-		56
8	811217114008	A.Dhanussh	50	-	-	-	-		37	-	-	-	•	-	74
9	811217114009	C.Dharanidharan	50	-	-	-	-	-	35	-	-	-	-	-	70
10	811217114010	N.Dharman	50	-	- 1	•	•	-	40	-	-	-	-	•	80
11	811217114013	M.Hariharasudhan	50	-	-	-	-	-	37	-	-	-	-	-	74
12	811217114014	A.Jawagar	50	-	-	-	- 1	-	41	- [-	-	-	-	82
13	811217114015	Karthick S	50	-	-	-	-	-	38	-	-	-	4	-	76
14	811217114016	D.Madhan	50	-	-	-	-	-	32	•	-	-	-	•	64
15	811217114018	M.Mohammed Faizal	50	-	-	-	-	-	31	-	-	-	-	-	62
16	811217114019	S.Mohanraj	50	-	-	-	-	-	42	-	-	-	-	•	84
17	811217114020	R.Munishwaran	50		-	-	-	- 1	31	- 1	- 1	- 1	-	-	. 62
18	811217114021	P.Murugan	50	-	-	•	•	-	A	-	-	- 1	-	•	Α
19	811217114022	P.Ponnar	50	-	- 1	•	-	-	38	-	-	-	-	-	76
20	811217114023	M.Prakash	50	-	-	- †	-	-	32	-	-	.	-	-	64
21	811217114025	M.Rajamuni	50	-	-	- †	-	-	42	-	-	•	-	-	84
22	811217114026	La.Ramanathan	50	-	-	•	-	-	36	-	-	-	-	-	72
23	811217114027	G.Sairam	50	-	-	•	-	-	47	-	- [-	-		94
24	811217114028	R.Sankaralingam	50	-		- 1	-	-	32	-		-		- [64

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		Dr. G.	Balalorishnan, M.E., Ph.D., Principal

Principal Indra Ganesan College of Engineering IG Valley, Madural Main Road

Manikandam. Trichy-670 12.

No. of Concession, Name

4501 4502 44 4 45 4503 4504 4505 46 4 47 48 49 50 Verified by 4 External Member Name and Signature: Internal Member Name and Signature: Overall Remarks: o-erdinator 10) HoD -578 Dr. G. Balakrishnan, M.E., Ph.D Principal Indra Ganesan College of Engineering IG Valley, Madurai Main Road Manikandam, Tochy-620.012.

		STUDENT FEEL	DBA	CK O	NEA	CULTY	7	
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	me of Department :	MECH Year / Sem:		IV/VIII		ty Name	Mr. P.	BABO
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i	Delivery of Lectures by	Interactive Communication						
2	, Use of Teaching Aids an	dKI	~					
3.	Level of Preparedness &	Knowledge Level	1					
44	Involvement in mentorin	g and guiding						
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7	Is the teacher distributing schedule?	answer scripts of students as per						a a server mely fingenerary metalolis org
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IQAC Cu-ordinator

Principal

Dr. G. Balakrishnan, M.E., Ph.D., Principal

Indra Ganesan College of Engineering IG Valley, Madurai Main Road Manikandam, Trichy-620 012.

Name of Department Subject Code & Name HoD/ MECHRNIK S.No. 0 yo, 90 2 0 1. v : -----Ch. <u>.</u> 4 ((08))? Is the teacher punctual to class? of IA while distributing? Use of Leaching Aids and ICT is the teacher covering content beyond syllabus is the teacher addressing grievances on answer scripts per schedule? is the teacher distributing answer scripts of students as schedule? is the teacher completing syllabus as per lecture I flective Time management Delivery of Lectures by Interactive Communication Involvement in mentoring and guiding Level of Preparedness & Knowledge Level MECH ME 8094 **OUESTIONS** ACADEMIC YEAR: Vear / Sem: (Approved by AICTE, New Delhi, Affiliated to Anna University, Chennai-25) IC Valley, Manikandam, Tiruchirappali, Tamii Nadu - 620 612, India ł computer 2021 -2022 INDRA GANESAN COLLEGE OF ENGINEERING STUDENT FEEDBACK ON FACULTY IN AN Excellent sa) THEORY COURSE Y IQAC Chordinator Intograted **Faculty Name** Ś Very Good J. γ 5 5 good З manufaduring Indra Ganesan College of Engineering Dr. G. Balakrishnan, M.E., Ph.D., Mr. IG Valley, Madurai Main Road Satisfactory N 2 Principal RAMOSH BABU Somewhat Satisfactory SEMESTER VII) System Not 0 Satisfactory Total Weight age Sien Percentage

Manikandam, Trichy-620 012.



Indra Ganesan College of Engineering

Madurai Main Road(NH-45B), Manikandam, Tiruchirappalli-620012 Approved by AICTE, New Delhi, Affiliated to Anna University, ChennaiNAAC Accredited, 2(F)&12(B)StatusInstitutionbyUGC



IGCE/EXAMCELL/IA/2021-22/Even/UT/001 INTERNAL ASSESSMENT_TEST – I

Test	Time: (FN)	11.30 am ta	o 1.00 pm	-	(AN) 3.3(0 pm to 5.00	
DATE	YEAR/	18.	.04.2022	19	.04.2022	20.	94.2622
BRANCH	SESSION	FN	AN	FN	AN	EN	AN
	R	CE8401	CE8402	MA8491	CE8491	CE8404	CE8403
CIVIL	III	CE8601	CE8602	CE8603	CE8604	EN8592	CE800
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	R	CS8491	CS8493	CS8451	CS8494	MA8402	CS8492
CSE	AH	CS8603	CS8691	CS8601	CS8602	CS8651	CS8075
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	II.	EE8401	EE8451	MA8491	EE8402	IC8451	EE8403
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	EV.	EE8015	1	EE8018			
Deleter	H	EC8491	MA8451	EC8451	GE8291	EC8453	EC8452
ECE	ALC.	MG8591	EC8691	EC8004	EC8652	EC8095	EC8651
	18	EC8072		EC8094	1		
	TI	ME8493	ME8491	ME8492	MA8452	ME8451	CE8395
MECH	III	ME8651	ME8691	ME8091	ME8693	ME8694	ME8692
	1V	MG8591		ME8094		unered bibling a	
THE REAL	THE R	CS8491	CS8493	CS8451	GE8291	MA8391	CS8492
IT	u	CS8091	CS8592	IT8601	IT8076	CS8092	IT8602
重要。		GE8076		IT8078			Waardo Mar. 700 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100

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	CALL PROFESSION	GARLAN DUTIONS	CO Madura Approv		E DF NH-458), Ma NewDelhi & A edites. 2(F) 5	ENI Allined	GINEE n, Teuchirapp a) Anna Unive aitration B) U	RING atili - 620 012 maley, Chemani AGC	2	D	Ì
	and the second se	Departmer /VIII-Sem	it of N	lechanical	Engineer	ring 20	21-2022 1			pan Kumar	
-		TTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTT		3			\$	1		1	SCC/CCA
BAY	9.15-10.50	10.10-11.00		11.15 - 12.90	12,10 - 100		1.45-2.30	238-3.15		3.50 - 6.15	4.80-05.05
MON	TATS	CIMS	165	TATS	POM	L	PROJE	CT WORK		PROJECT	CCA/SCC
TUE	POM	CIMS	R	TATS	PROJECT	UN	PROJE	CT WORK	R	PROJECT	CCA/SCC
WED	PROJEC	TWORK	A	POM	TATS	CH	CIMS	TATS	A	TATS	CCA/SCC
THU	PROJEC	T WORK		PROJEC	T WORK		PROJE	CT WORK		PROJECT	CCA/SCC
FRI	PROJEC	T WORK		PROJEC	I' WORK		РОМ	CIMS		TATS	CCA/SCC
SUBJECT	En Strang		counts	ENAME	2 - H 91		TRP CODE	HOURS	111	TAPP IN CHA	RE
MG8591	Principle of I	Management				Contract And		3/45	Dr.Thao	garasu Prof/M	ech
ME8094	Computer Int	egrated Manuf	acturing	Systems				3/45	Mr. R.R	amesh Babu, F	IOD/Mech
ME8811	Project Work						IGCE0308	10/300	Mr. R.R.	amesh Babu, H	IOD/Mech
	CCA/SCC							5 hours/week			
	TATS							7 hours/week			
	TOTAL							16/390			

5:0 Br. G. Balakrishnan, M.E., Ph.D., Principali Indra Gamaan College of Engineering IG Valley, Madurai Main Road Mailkandam, Trichy 6820012.



Indra Ganesan College of Engineering

Madurai Main Road(NH-45B), Manikandam, Tiruchirappalli-620012 Approved by AICTE, New Delhi, Affiliated to Anna University, ChennaiNAAC Accredited, 2(F)&12(B)StatusInstitutionbyUGC



IGCE/EXAMCELL/IA/2021-22/Even/UT/005 **MODEL EXAM-I**

Test Time: (AN)2.00 pm to 5.00 pm

DATE	YEAR/		21.06.2022		23.06.202	2 24.06.2022	25.06.2022
BRANCH	SESSION	AN	AN	AN	AN	AN	AN
	THE OWNER	CE8401	CE8402	MA8491	CE8491	CE8404	CE8403
CIVIL	10	CE8601	CE8602	CE8603	CE8604	EN8592	CE8005
	IV	GE8076		CE8022			
	¥.	CS8491	CS8493	CS8451	CS8494	MA8402	CS8492
CSE	m	CS8603	CS8691	CS8601	CS8602	CS8651	CS8075
	T. IV	GE8076		CS8080			
Seattle State		EE8401	EE8451	MA8491	EE8402	IC8451	EE8403
ERE	111	EE8601	EE8691	EE8602	EE8661	EE8002	EE8005
化成本 日	IY	EE8015		EE8018			
	Have	EC8491	MA8451	EC8451	GE8291	EC8453	EC8452
ECE	712	MG8591	EC8691	EC8004	EC8652	EC8095	EC8651
	ŧV	EC8072		EC8094			
MECH	1	ME8493	ME8491	ME8492	MA8452	ME8451	CE8395
	100	ME8651	ME8691	ME8091	ME8693	ME8694	ME8692
	3V	MG8591		ME8094	ar sadigleyyaya		
п	9	CS8491	CS8493	CS8451	GE8291	MA8391	CS8492
	Ū	CS8091	CS8592	FT8601	IT8076	CS8092	IT8602
	IV	GE8076		IT8078			



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IGCE/EXAMCELL/IA/2021-22/Even/UT/003 **INTERNAL ASSESSMENT TEST - II**

Test	Time: (FN) 1	1.30 am to	1.00 pm	- 6	AN) 3.30	pm to 5.00	
DATE	YEAR/	16.05.2022		17.05.2022		18.05.2022	
BRANCH	SESSION	FN	AN	FN	AN	FN	AN
CIVIL	I	CE8401	CE8402	MA8491	CE8491	CE8404	CE8403
	UL	CE8601	CE8602	CE8603	CE8604	EN8592	CE8005
	EN EN	GE8076		CE8022			
CSE	an at	CS8491	CS8493	CS8451	CS8494	MA8402	CS8492
	m	CS8603	CS8691	CS8601	CS8602	CS8651	CS8075
	18	GE8076		CS8080			1
ERE	U	EE8401	EE8451	MA8491	EE8402	IC8451	EE8403
	ST III	EE8601	EE8691	EE8602	EE8661	EE8002	EE8005
	IV.	EE8015	2	EE8018			1
	1	EC8491	MA8451	EC8451	GE8291	EC8453	EC8452
ECE	ш	MG8591	EC8691	EC8004	EC8652	EC8095	EC8651
	IV	EC8072		EC8094			н 1
месн	II	ME8493	ME8491	ME8492	MA8452	ME8451	CE8395
	HI	ME8651	ME8691	ME8091	ME8693	ME8694	ME8692
	IV SA	MG8591		ME8094			
п	ų	CS8491	CS8493	CS8451	GE8291	MA8391	CS8492
	IR	CS8091	CS8592	IT8601	IT8076	CS8092	IT8602
	THE MAN	GE8076	ha v	IT8078			interferentian. Solid is a numerican second s



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Dr. G. Balakrishnan, M.E., Ph.D., Principal Indra Ganesan College of Engineering IG Valley, Madurai Main Road Manikandam, Trichy-620 012.



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IGCE/EXAMCELL/IA/2021-22/Even/UT/006 **RE MODEL EXAM-I**

Test Time: (AN)2.00 pm to 5.00 pm

DATE	YEAR!	29.06.2022	30.06.2022	01.06.2822	04.07.2023	1 105,07.2022	86.87.202
BRANCH	SESSION	AN	AN	AN	AN	AN	AN
CIVIL	n	CE8401	CE8402	MA8491	CE8491	CE8404	CE8403
	III III	CE8601	CE8602	CE8603	CE8604	EN8592	CE8005
	IV	GE8076		CE8022			
1 Participa	R	CS8491	CS8493	CS8451	CS8494	MA8402	CS8492
CSE	ar	CS8603	CS8691	CS8601	CS8602	CS8651	CS8075
	N.	GE8076		CS8080			
EEE		EE8401	EE8451	MA8491	EE8402	IC8451	EE8403
		EE8601	EE8691	EE8602	EE8661	EE8002	EE8005
	15	EE8015	1	EE8018			- 9,184777797
	1 . H	EC8491	MA8451	EC8451	GE8291	EC8453	EC8452
ECE	313	MG8591	EC8691	EC8004	EC8652	EC8095	EC8651
		EC8072		EC8094	11		
MECH	11	ME8493	ME8491	ME8492	MA8452	ME8451	CE8395
	TI .	ME8651	ME8691	ME8091	ME8693	ME8694	ME8692
	IV	MG8591		ME8094	*****	alerating again and face of the second s	
п	n n	CS8491	CS8493	CS8451	GE8291	MA8391	CS8492
	n at	CS8091	CS8592	IT8601	IT8076	CS8092	IT8602
	1.15	GE8076		IT8078			•

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Dr.G.Balakrishnan, ME, Ph.D., PRimagizal InddaaGaaneeaanCottlegeoffEAgaidee77183 ICG/Allhey/Maidusai/MainRBaad Maanikaddam Tidsby66000222.



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IGCE/EXAMCELL/IA/2021-22/Even/UT/004 **INTERNAL ASSESSMENT RE TEST - II**

Test Time: (FN) 11.30 am to 1.00 pm (AN) 3.30 pm to 5.00 pm

DATE	YEAR/	23.05.2022		24.05,2022		25.05.2022	
BRANCH	SESSION	FN	AN	FIN	AN	FN	AN
CIVIL	and the second second	CE8401	CE8402	MA8491	CE8491	CE8404	CE8403
	U	CE8601	CE8602	CE8603	CE8604	EN8592	CE8005
	EV	GE8076	1	CE8022			
CSE	H	CS8491	CS8493	CS8451	CS8494	MA8402	CS8492
	THE	CS8603	CS8691	CS8601	CS8602	CS8651	CS8075
	EN.	GE8076	-	CS8080			and a second second second
		EE8401	EE8451	MA8491	EE8402	IC8451	EE8403
EEE		EE8601	EE8691	EE8602	EE8661	EE8002	EE8005
	THE THE	EE8015	1	EE8018			
	- REAL	EC8491	MA8451	EC8451	GE8291	EC8453	EC8452
ECE	IRI	MG8591	EC8691	EC8004	EC8652	EC8095	EC8651
and the second	I.IV	EC8072		EC8094			T
MECH	I	ME8493	ME8491	ME8492	MA8452	ME8451	CE8395
	EEL	ME8651	ME8691	ME8091	ME8693	ME8694	ME8692
	EV.	MG8591		ME8094			
п	n	CS8491	CS8493	CS8451	GE8291	MA8391	CS8492
	ar	CS8091	CS8592	IT8601	IT8076	CS8092	IT8602
	28	GE8076		IT8078			



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